# Evaluating Cognitive Deficits in 3xTg-AD Mice Using a Linear **Reorientation Task**

### FSU UNDERGRADUATE RESEARCH **OPPORTUNITY PROGRAM**

## Aayushi Ranjan, Rebecca Branson, Isabel I. Coiduras and Dr. Aaron Wilber

## Introduction

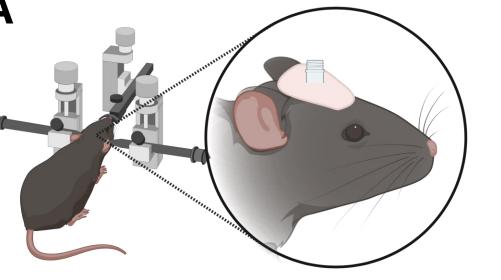
- Alzheimer's disease is a progressive neurodegenerative disorder characterized by cognitive decline, memory loss, and impaired spatial navigation.
- Our lab has demonstrated impaired spatial orientation in 6-month-old 3xTg-AD mice on a hybrid (129x1/C57BL6) background.
- For this study, we used 3xTg-AD mice bred onto a pure C57BL/6 background, as this strain exhibits more stable circadian rhythms
- We previously demonstrated impaired spatial orientation in 6-month-old 3xTg-AD mice on a hybrid (129x1/C57BL6) background (Stimmell et al. 2019).
- We designed a behavioral paradigm to assess spatial learning and memory by requiring mice to navigate a linear track using distal environmental cues and learn to stop at a certain zone.
- We used a genetically engineered model that expresses amyloid-beta plaques and tau pathology, recapitulating key features of AD.
- We utilized a brain stimulation reward system, specifically in the Medial Forebrain Bundle to reinforce correct stopping behavior within an unmarked reward zone.
- Findings contribute to evidence supporting spatial navigation tasks as a robust measure of cognitive decline in AD models, providing insights into early intervention strategies.
- We hypothesized that 6-month female 3xTg-AD C57BL/6 mice would have impaired task performance compared to controls, indicating impaired spatial reorientation.

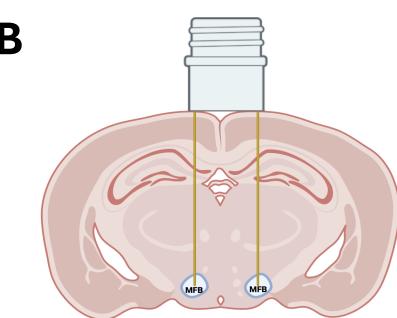
## **General Methods**

Subjects & Design: Six-month-old female 3xTg-AD mice on C57BL/6 background and wild-type (WT) controls were used to assess spatial learning and memory during the dark cycle.

**Surgery:** Two bipolar stimulating electrodes were implanted bilaterally in the medial forebrain bundle.







Task Overview: Mice were trained to navigate a linear track to an unmarked goal location in two distinct phases:

- Alternating Phase: Mice traveled back and forth between two endpoints for a water reward consumed in enclosed start box.
- **Goal-Learning Phase:** Mice had to stop within unmarked reward zone during the outbound trajectory to receive a brain stimulation reward. **Histological Validation:**

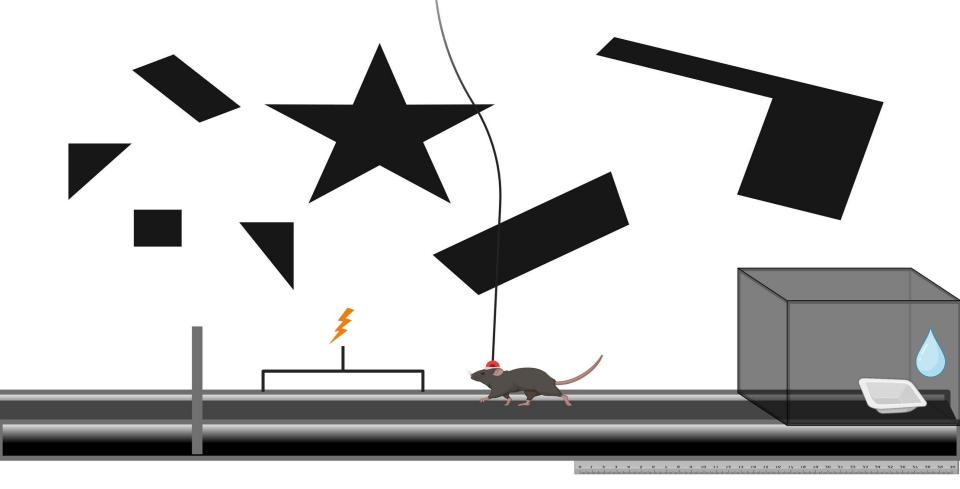
•Following behavioral testing, mice were euthanized for brain tissue collection. •Using a sliding microtome, frozen tissue was coronally sectioned and collected at 40 um and evenly placed in a series of six wells.

- Six types of immunohistochemical staining confirmed AD pathology and
- medial forebrain bundle (MFB) electrode placement (see Table).

Stain	Target
MOC22	Amyloid deposits
MOC78	Plaques and unique populations of intraneuronal and intr amyloid; center of nascent neuritic plaques.
IBA1	Microglia and macrophage markers.
Ptau	Accumulation of phosphorylated tau in the brain
6E10	All forms of amyloid beta and the precursor APP
NeuN	Visualize neurons in brain tissue
GFAP	Visualize astrocytes in brain tissue

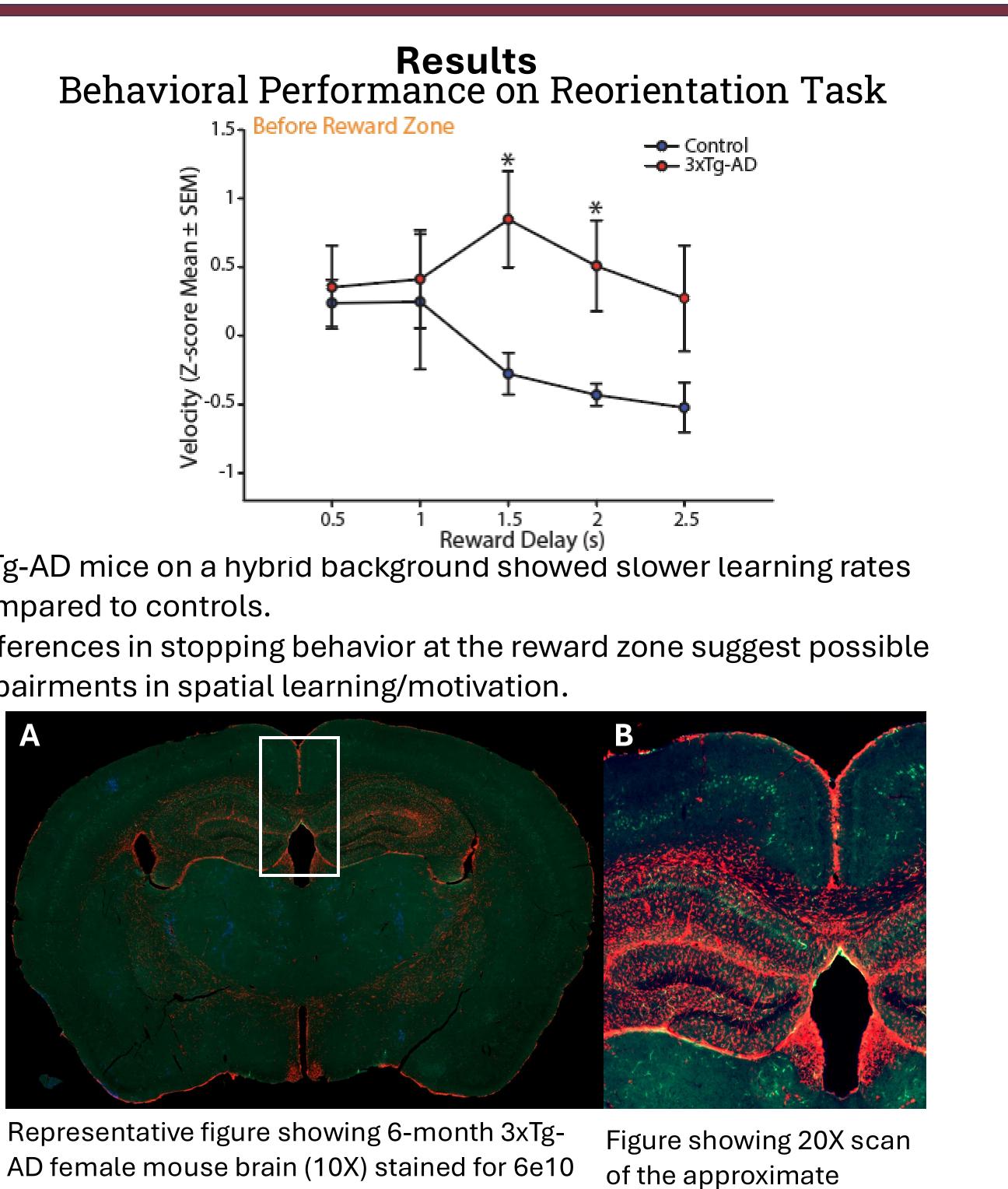
tranuclear

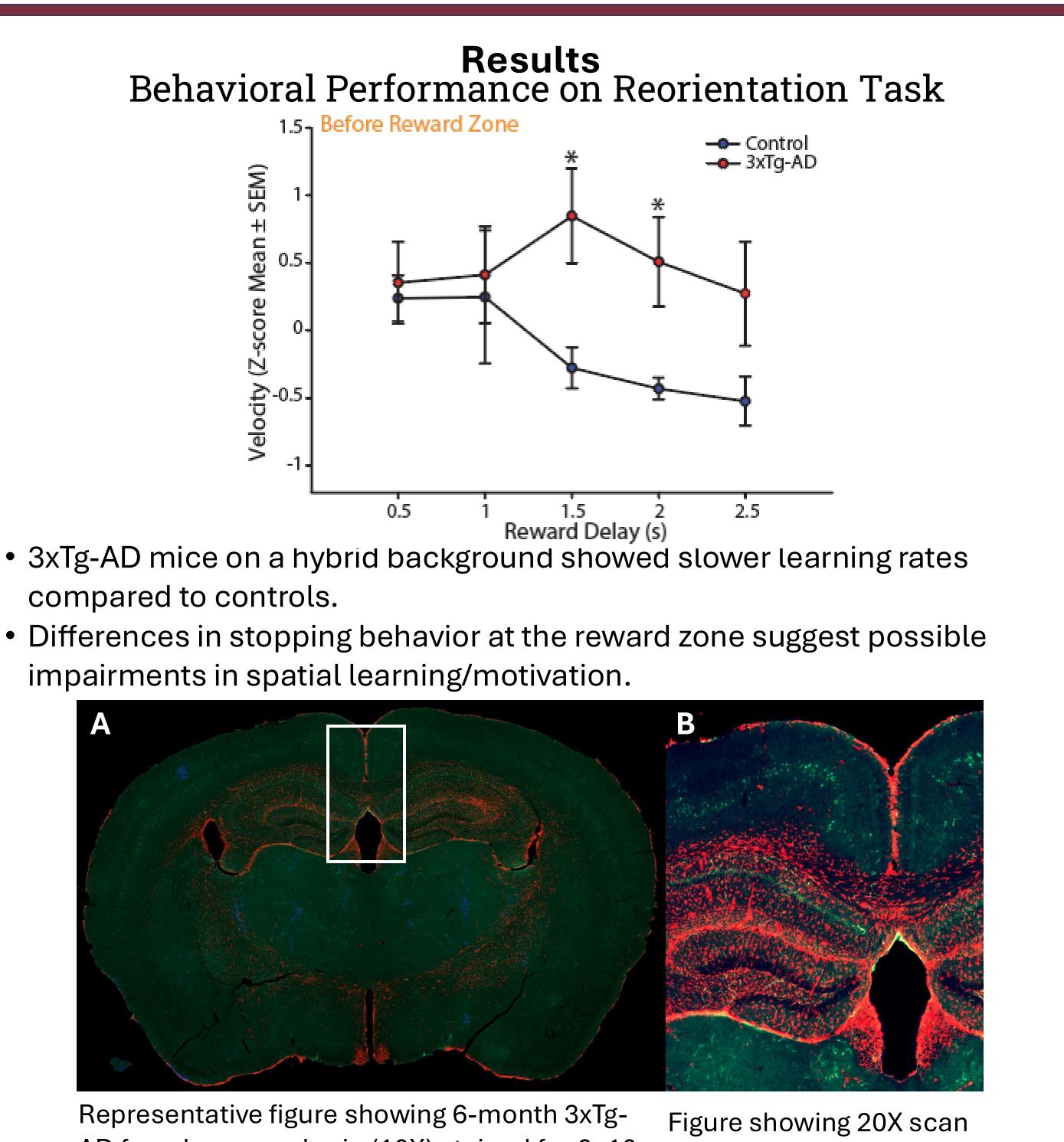
- **Experimental Procedure:**
- Mice were individually housed in a 12-hour light/dark cycle with ad libitum access to food and were water-restricted to maintain motivation for the task.
- Custom software automated reward delivery upon correct stopping behavior within the unmarked zone.
- The linear track was repositioned randomly between trials, requiring mice to rely on distal environmental cues for spatial reorientation rather than egocentric strategies.
- Training continued until stable task performance was observed, specifically 80% pass rate 3 out of 4 days in a row.
- Performance was measured by the number of correct stops within the reward zone.



## **Data Collection & Analysis:**

Statistical comparisons between 3xTg-AD and WT mice were conducted using MATLAB.





AD female mouse brain (10X) stained for 6e10 (green), GFAP (Red), NeuN (blue) (A).

## **Experimental Methods**

An overhead camera system tracked the mice's position in real time.

location marked in A.

